

- ▶ Direct drive brushless motor
- ▶ Fully integrated with encoder and bearing
- ▶ Low cogging torque
- ▶ Precise homing through index pulse
- ▶ Low speed and high speed windings

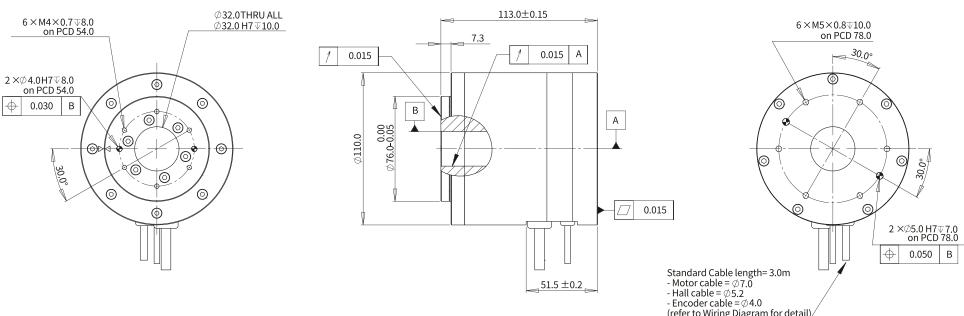
## ADR110-B113

ADR110-B113

Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C <sup>①</sup>	T <sub>Cn</sub>	Nm	1.9	1.9
Peak Torque	T <sub>Pk</sub>	Nm	5.8	5.8
Torque Constant ±10%	K <sub>T</sub>	Nm/Arms	0.65	0.32
Back EMF constant ±10%	K <sub>ε</sub>	Vpeak/rpm	0.055	0.028
Motor Constant @25°C	K <sub>M</sub>	Nm/Sqz(LW)	0.30	0.30
Resistance (L-L) @25°C ±10% <sup>②</sup>	R <sub>ZS</sub>	Ω	3.20	0.80
Inductance (L-L) ±20% <sup>③</sup>	L	mH	17.15	4.29
Electrical time constant	T <sub>E</sub>	ms	5.36	5.36
Continuous Current @100°C <sup>④</sup>	I <sub>Cn</sub>	Arms	3.0	6.0
Peak Current	I <sub>Pk</sub>	Arms	9.0	18.0
Continuous Power Dissipation @100°C <sup>⑤</sup>	P <sub>Dn</sub>	W	55.7	55.7
Max. Coil Temperature	T <sub>max</sub>	°C	100.0	100.0
Thermal Dissipation Constant <sup>⑥</sup>	K <sub>thn</sub>	W/°C	0.7	0.7
Max. Bus Voltage	U <sub>bus</sub>	Vdc	600.0	600.0
Pole Number	p	-	16	16
Rec. Max Speed @230V AC <sup>⑦</sup>	Ω <sub>max</sub>	rpm	1700	2000
Mechanical Parameters				
Overall Mass	m <sub>n</sub>	kg	3.20	3.20
Rotor Inertia	J <sub>r</sub>	kg·m <sup>2</sup>	3.086E-04	3.086E-04
Axial Runout <sup>⑧</sup>	-	μm	15	15
Radial Runout <sup>⑨</sup>	-	μm	15	15
Max Axial Load (Upright Mounting) <sup>⑩</sup>	-	N	439	439
Max Axial Load (Inverted / Wall mounting)	-	N	35	35
Max Moment Load (Upright Mounting)	-	Nm	25	25
Max Moment Load (Inverted / Wall Mounting)	-	Nm	2.8	2.8
Encoder Parameters				
ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	3005	3005
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	240400	240400
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	480800	480800
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	1202000	1202000
Accuracy with Error Mapping <sup>⑪</sup>	-	arc sec	+/-5.4	+/-5.4
Repeatability <sup>⑫</sup>	-	arc sec	+/-2.7	+/-2.7
Other Information				
Insulation Class		Class B (130°C)		
Protection Grade		IP40		
Compliance with Global Standards		RoHS, CE, UL (option)		
Ambient Temperature	Operation	0°C to 40°C (non-freezing)		
	Storage	-15°C to 70°C (non-freezing)		
Ambient Humidity	Operation	10%RH to 80%RH (non-condensing)		
	Storage	10%RH to 90%RH (non-condensing)		
Recommended Ambience		Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.		

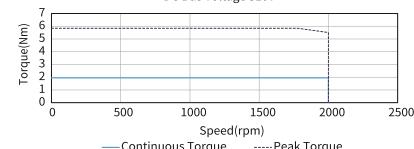
<sup>①</sup> Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.  
<sup>②</sup> Resistance is measured by DC current with standard 3 m cable.  
<sup>③</sup> Inductance is measured by current frequency of 1 kHz.  
<sup>④</sup> The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.  
<sup>⑤</sup> The runout value in parenthesis is optional.  
<sup>⑥</sup> Please refer to the illustration for different mountings.  
<sup>⑦</sup> Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.  
 The contents of datasheet are subjected to change.

### Dimension

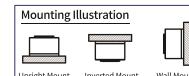
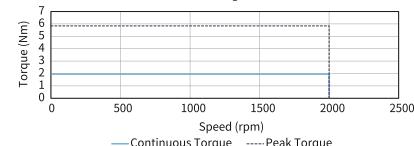


### ■ Torque-Speed Curve

Torque Speed Curve ADR110-B113 Series Connection  
DC Bus Voltage 310V



Torque Speed Curve ADR110-B113 Parallel Connection  
DC Bus Voltage 310V





## ADR135-B148

ADR135-B148

Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C	$T_{cn}$	Nm	11.0	11.0
Peak Torque	$T_{pk}$	Nm	32.9	32.9
Torque Constant $\pm 10\%$	$K_t$	Nm/Arms	3.66	1.83
Back EMF constant $\pm 10\%$	$K_e$	Vpeak/rpm	0.313	0.156
Motor Constant @25°C	$K_m$	Nm/Sqr(1W)	0.91	0.91
Resistance (L-L) @25°C $\pm 10\%$	$R_{25}$	Ω	10.70	2.70
Inductance (L-L) $\pm 20\%$	$L$	mH	72.76	18.63
Electrical time constant	$\tau_e$	ms	6.80	6.90
Continuous Current @100°C	$I_{cn}$	Arms	3.0	6.0
Peak Current	$I_{pk}$	Arms	9.0	18.0
Continuous Power Dissipation @100°C	$P_{dn}$	W	186.2	187.9
Max. Coil Temperature	$T_{max}$	°C	100.0	100.0
Thermal Dissipation Constant	$K_{thn}$	W/°C	2.5	2.5
Max. Bus Voltage	$U_{bus}$	Vdc	600.0	600.0
Pole Number	$p$	-	16	16
Rec. Max Speed @230V AC	$\Omega_{max}$	rpm	330	745

## Mechanical Parameters

Overall Mass	$m_{in}$	kg	5.70	5.70
Rotor Inertia	$J_r$	kg·m <sup>2</sup>	1.332E-03	1.332E-03
Axial Runout	-	μm	15	15
Radial Runout	-	μm	15	15
Max Axial Load (Upright Mounting)	-	N	604	604
Max Axial Load (Inverted / Wall mounting)	-	N	56	56
Max Moment Load (Upright Mounting)	-	Nm	45	45
Max Moment Load (Inverted / Wall Mounting)	-	Nm	5.0	5.0

## Encoder Parameters

ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	4103	4103
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	328240	328240
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	656480	656480
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	1641200	1641200
Accuracy with Error Mapping	-	arc sec	+/-4	+/-4
Repeatability	-	arc sec	+/-2	+/-2

## Other Information

Insulation Class	Class B (130°C)		
Protection Grade	IP40		
Compliance with Global Standards	RoHS, CE, UL (option)		
Ambient Temperature	Operation	0°C to 40°C (non-freezing)	
	Storage	-15°C to 70°C (non-freezing)	
Ambient Humidity	Operation	10%RH to 80%RH (non-condensing)	
	Storage	10%RH to 90%RH (non-condensing)	
Recommended Ambience	Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.		

④ Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.

⑤ Resistance is measured by DC current with standard 3 m cable.

⑥ Inductance is measured by current frequency of 1 kHz.

⑦ The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.

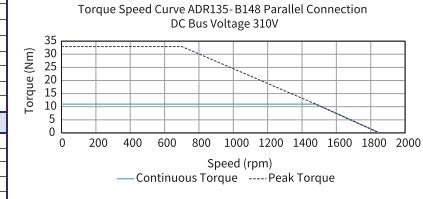
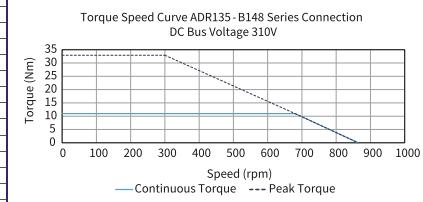
⑧ The runout value in parenthesis is optional.

⑨ Please refer to the illustration for different mountings.

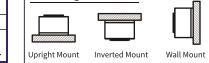
⑩ Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.

The contents of datasheet are subjected to change.

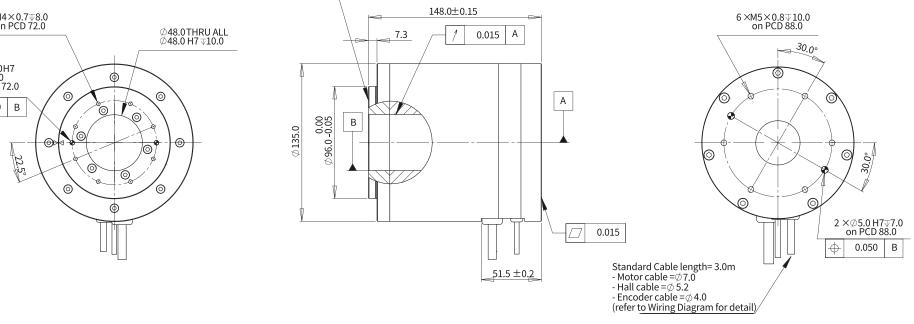
## Torque-Speed Curve



## Mounting Illustration



## Dimension

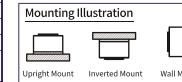
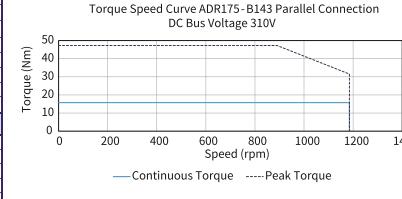
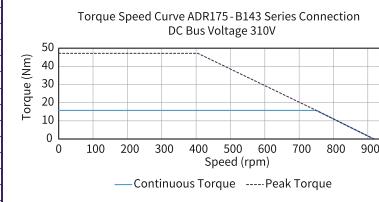


## ADR175-B143

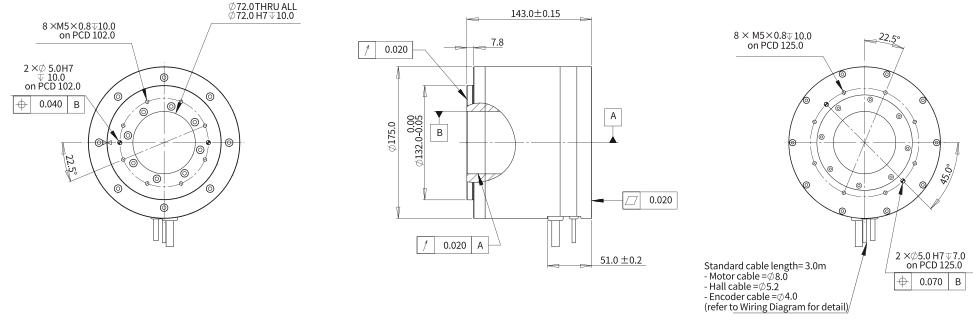
ADR175-B143

Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C	$T_{cn}$	Nm	15.7	15.7
Peak Torque	$T_{pk}$	Nm	47.2	47.2
Torque Constant $\pm 10\%$	$K_t$	Nm/Arms	3.93	1.97
Back EMF constant $\pm 10\%$	$K_e$	Vpeak/rpm	0.336	0.168
Motor Constant @25°C	$K_m$	Nm/Sqr(1W)	1.40	1.41
Resistance (L-L) @25°C $\pm 10\%$	$R_{25}$	Ω	5.27	1.30
Inductance (L-L) $\pm 20\%$	$L$	mH	45.72	11.27
Electrical time constant	$\tau_e$	ms	8.67	8.67
Continuous Current @100°C	$I_{cn}$	Arms	4.0	8.0
Peak Current	$I_{pk}$	Arms	12.0	24.0
Continuous Power Dissipation @100°C	$P_{dn}$	W	163.1	160.9
Max. Coil Temperature	$T_{max}$	°C	100.0	100.0
Thermal Dissipation Constant	$K_{thn}$	W/°C	2.2	2.1
Max. Bus Voltage	$U_{bus}$	Vdc	600.0	600.0
Pole Number	$p$	-	16	16
Rec. Max Speed @230V AC	$\Omega_{max}$	rpm	400	880

## Torque-Speed Curve



## Dimension





## ADR220-B217

ADR220-B217

Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C	T <sub>c</sub>	Nm	94.9	94.9
Peak Torque	T <sub>p</sub>	Nm	284.6	284.6
Torque Constant ±10%	K <sub>t</sub>	Nm/Arms	17.57	5.86
Back EMF constant ±10%	K <sub>e</sub>	Vpeak/rpm	1.502	0.591
Motor Constant @25°C	K <sub>m</sub>	Nm/Sqr(W)	4.47	4.37
Resistance (L-L) @25°C ±10%	R <sub>25</sub>	Ω	10.32	1.20
Inductance (L-L) ±20%	L	mH	106.70	11.90
Electrical time constant	T <sub>e</sub>	ms	10.34	9.92
Continuous Current @100°C	I <sub>c</sub>	Arms	5.40	16.20
Peak Current	I <sub>p</sub>	Arms	16.2	48.6
Continuous Power Dissipation @100°C	P <sub>c</sub>	W	581.9	608.9
Max. Coil Temperature	T <sub>max</sub>	°C	100.0	100.0
Thermal Dissipation Constant	K <sub>thn</sub>	W/°C	7.8	8.1
Max. Bus Voltage	U <sub>bus</sub>	Vdc	600.0	600.0
Pole Number	p	-	24	24
Rec. Max Speed @230V AC	Q <sub>max</sub>	rpm	50	260

## Mechanical Parameters

Overall Mass	m <sub>n</sub>	kg	23.4	23.4
Rotor Inertia	J <sub>r</sub>	kg·m <sup>2</sup>	2.522E-02	2.522E-02
Axial Runout	-	μm	25	25
Radial Runout	-	μm	25	25
Max Axial Load (Upright Mounting)	-	N	1669	1669
Max Axial Load (Inverted / Wall mounting)	-	N	105	105
Max Moment Load (Upright Mounting)	-	Nm	85	85
Max Moment Load (Inverted / Wall Mounting)	-	Nm	9.4	9.4

## Encoder Parameters

ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	5071	5071
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	405680	405680
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	811360	811360
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	2028400	2028400
Accuracy with Error Mapping	-	arc sec	+/-4	+/-4
Repeatability	-	arc sec	+/-2	+/-2

## Other Information

Insulation Class	Class B (130°C)		
Protection Grade	IP40		
Compliance with Global Standards	RoHS, CE, UL (option)		
Ambient Temperature	Operation	0°C to 40°C (non-freezing)	
	Storage	-15°C to 70°C (non-freezing)	
Ambient Humidity	Operation	10%RH to 90%RH (non-condensing)	
	Storage	10%RH to 90%RH (non-condensing)	
Recommended Ambience	Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.		

① Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.

② Resistance is measured by DC current with standard 3 m cable.

③ Inductance is measured by current frequency of 1 kHz.

④ The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.

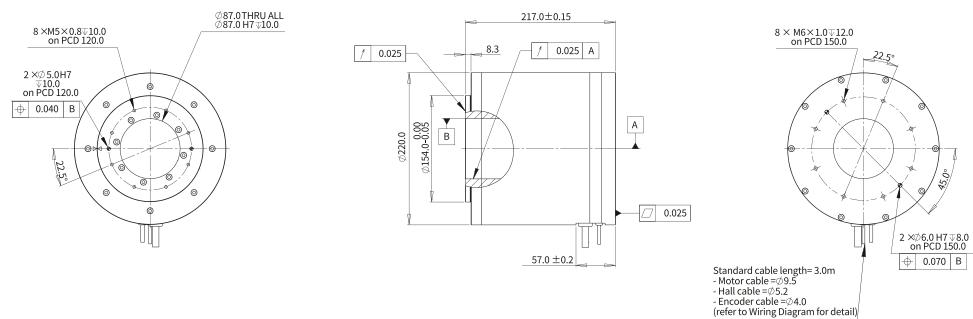
⑤ The runout value in parenthesis is optional.

⑥ Please refer to the illustration for different mountings.

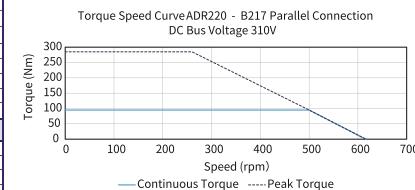
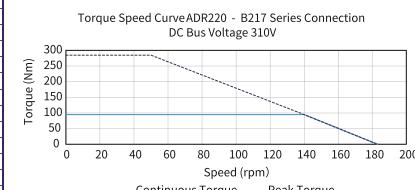
⑦ Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.

The contents of datasheet are subjected to change.

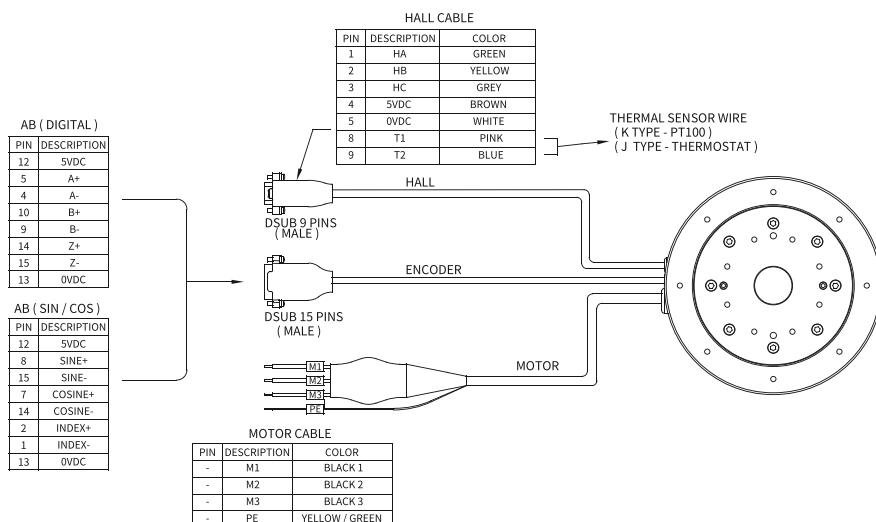
## Dimension



## Torque-Speed Curve



## Motor Cable Connection



## Part Numbering

ADR110-B136-S-J-H9D-3.0-FB-AB-3005-SINCOS-P15

Motor:

Model:

Winding:

Thermal Sensor:

Hall Cable Options:

Runout:

Interpolation Options:

Encoder Options:

Motor Cable Options:

Cable Length (m):

- H9D = With built-in hall sensor, comes with 9-Pins D-Sub Connector.
- NH = Without Built-in Hall Sensor but with Thermal Sensor.
- FB = With ferrite bead.
- P15 = Axial Runout 15um, Radial Runout is 15um.

# ADR-B Series

Introduction | Sizing Guide | Frequently Asked Questions

Linear Motors | Voice Coil Motors

Direct Drive

Rotary Motors

Motion Control of Gantry Stages

Akribis systems

**ADR135-B121-S-J-H9D-3.0-FB-AB-4103-SINCOS-P15**

Motor:  
[ADR135](#)

Model:  
[B121 / B148](#)

Winding:  
[S-Series / P=Parallel](#)

Thermal Sensor:  
[J=Thermostat\(standard\) / K=PT100\(RTD\)](#)

Hall Cable Options:  
[H9D / NH](#)

Runout:  
[P15](#)

Interpolation Options:  
[SINCOS  
80X / 160X / 400X](#)

Encoder Options:  
[AB-4103](#)

Motor Cable Options:  
[FB](#)

Cable Length (m):  
[3.0](#)

① H9D = With Built-in hall sensor, comes with 9-Pins D-Sub Connector.  
② NH = Without Built-in Hall Sensor but with Thermal Sensor.  
③ FB = With ferrite bead.  
④ P15 = Axial Runout 15um, Radial Runout is 15um.

**ADR175-B180-P-J-NH-3.0-FB-AB-5071-SINCOS-P20**

Motor:  
[ADR175 / ADR220](#)

Model:  
[ADR175-B143 / B180  
ADR220-B167 / B217](#)

Winding:  
[S-Series / P=Parallel](#)

Thermal Sensor:  
[J=Thermostat\(standard\) / K=PT100\(RTD\)](#)

Hall Cable Options:  
[H9D / NH](#)

Runout:  
[P20  
P25](#)

Interpolation Options:  
[SINCOS  
80X / 160X / 400X](#)

Encoder Options:  
[AB-5071](#)

Motor Cable Options:  
[FB](#)

Cable Length (m):  
[3.0](#)

① H9D = With Built-in hall sensor, comes with 9-Pins D-Sub Connector.  
② NH = Without Built-in Hall Sensor but with Thermal Sensor.  
③ FB = With ferrite bead.  
④ ADR175 : P20 = Axial Runout 20um, Radial Runout is 20um.  
ADR220 : P25 = Axial Runout 25um, Radial Runout is 25um.