

ZERO COGGING | HIGHLY EFFICIENT ARCHITECTURE | OPTIMIZED ROTOR INERTIA SPACE HERITAGE | LIGHTWEIGHT COMPOSITE STATOR | SCALABLE SIZE AND POWER

Data Sheet Model Number:

TGR 60-28

ThinGap's TGR Series includes numerous high performance brushless permanent magnet motors. The TGR Series targets reaction wheel applications where a high efficiency, weight optimized solution with dynamic response capabilities is desired.



Motor Parameter Table

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Continuous Parameters	Units	Atmosphere	Vacuum
Continuous Torque @ Max Speed	N-m	0.46	0.08
Max Continuous Speed	RPM	16000	16000
Max Continuous Power	W	770	134
Required Motor Voltage @ Max Speed	$V_{ m pkl-l}$	53.6	51.0
Max Continuous Phase Current @ Max Speed	A _{RMS}	12.4	2.2
Peak Parameters@Max Speed	Units	Atmosphere	Vacuum
Peak Torque (1 sec)*	N-m	1.67	1.61
Peak Phase Current (1 sec)	A _{RMS}	45.3	43.6
Peak Power (1 sec)*	W	2798	2698
Peak Torque (3 sec)*	N-m	1.04	0.935
Peak Phase Current (3 sec)	A _{RMS}	28.0	25.2
Peak Power (3 sec)*	W	1743	1567
Motor Constants	Units	Common Value	
Voltage Constant (I-I)	V _{pkl-I} /rad/s	0.030	
Voltage Constant (I-I)	V _{pkl-l} /kRPM	3.185	
Torque Constant	N-m/A _{RMS}	0.037	
Motor Constant	N-m/√W	0.072	
Electrical Parameters	Units	Common Value	
Motor Resistance @ 20°C	Ω	0.177	
Motor Resistance @ Max Temperature	Ω	0.248	
Inductance	μН	8.05 ± 20%	
Number of Magnetic Poles	ea	6	
Electrical Frequency @ Max Speed	Hz	1067	
Mechanical Parameters	Units	Common Value	
Rotor Inertia	kg-m ²	1.38E-04	
Outer Diameter	mm	60	
Through Hole Diameter	mm	28	
Axial Height	mm	28.5	
Rotor Mass	kg	0.239	
Stator Mass	kg	0.034	
Part Set Mass	kg	0.273	
Temperature Parameters	Units	Common Value	
Max Stator Temperature	°C	130	
Max Rotor Temperature	°C	85	

ThinGap's TGR Line of Brushless motor kits designed for use in reaction wheel applications; both in atmosphere and vacuum. These motor kits are available in sizes ranging from 29mm to 79 mm

Derated Specifications for Vacuum

Continuous torque of up to 0.08 N-m and a rated speed of up to 16000 RPM.

Motor Controller Recommendation

3-Phase Controller

High Frequency PWM power input



^{*} Current value takes into account temperature losses during operation.